



***CONTROL, PROTECTION AND  
VISUALIZATION  
ELECTRONIC MANUAL CEN-  
TRALITE  
FOR GENERATING SETS***

***CMD2.0***



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## **1. DESCRIPTION AND GENERAL CHARACTERISTICS**

The protection switchboard is cased in an insulating box which keeps off electromagnetic radiations. It includes visualization of electrical parameters and optical signals.

This device integrates the possibility of starting the motor in a manual or automatic way (by free voltage contact), and protecting it from possible breakdowns during operation. Management is effected in the interior, through an electronic circuit controlled by microprocessor.

The general characteristics are the following:

- Voltage supply 12/24V.
- Protections:
  - Overvoltage
  - Subvoltage
  - Asymmetry
  - Overcurrent
  - Overfrequency (overspeed)
  - Subfrequency (loss of speed)
  - Etc.
- Automatic filling of fuel tank.
- Readings:
  - Voltages
  - Currents
  - Fuel level
  - Pressure
  - Temperature
  - Battery voltage
  - Hour counter
  - Tachometer (R.P.M. indicator)
  - Frequency
- Start by free voltage contact.
- Possibility of programming the type of action to accomplish after an alarm.
- 3-phase set sensor.



## **2. INSTALLATION MATERIALS**

The following elements are necessary for the complete installation of the CMD2.0 device in a generating set:

- Cmd2.0.
- 3 current transformers /5Aac.
- Oil pressure sensor (vdo code 360.081/030/009).
- Water temperature sensor (vdo code 323.803/004/001).
- Level sensor ( variable resistance gauger 0 to 330 ohm).
- Thermostat.
- Pressurestat.
- Relay boards 802ctreles02-12/24 and 802ctreles02-12/24s.

**IMPORTANT: Before carrying out any tasks on the current transformers, verify that no current is circulating in the primary transformer, since if we open the secondary of an current transformer through which a current is circulating, extremely high voltages are produced, which can injure or even kill the person manipulating them.**

**Installation must be accomplished by qualified specialist technicians in strict observance of all electrical regulation codes applicable.**

Wiring connections to the battery of the motor should be accomplished by means of two 2.5 mm<sup>2</sup>conducting cables.

In noisy environments (i.e., gas motors with high voltage ignitions, etc), the battery wiring must be a 2.5 mm<sup>2</sup> twisted pair.



### **3. FRONT PANEL.**

In addition to an alarm codes chart, the following elements are found on the frontal part of the CMD2.0 protection, control and visualization device:

#### **Start switch**

#### **V(-).**

To select the voltage that will be visualized in display 1. The switchboard shows the voltages between phases of the generating set: L1-L2 (VRS), L2-L3(VST), L3-L1(VTR).

#### **A(+).**

To select the current measure showed in display 2. The switchboard offers currents readings of the three phases (IL1, IL2, IL3).

#### **D3(-).**

To select, from four possible measures (frequency reading, battery voltage, fuel level or alarm code), the measure to be visualized in display 3.

#### **D4(-).**

Similarly to D3, D4 permits to choose which of the four measures offered by display 4 to visualize (hour counter, revolutions counter, water temperature, oil pressure).

#### **AUT operation mode.**

To select the automatic operation mode.

#### **STOP/RESET operation mode.**

To select the STOP operation mode. By maintaining this button pressed for 5 seconds, the centralite executes a reset operation.

#### **START/MAN operation mode.**

Starts the motor and selects the manual operation mode.



The following optical signals can also be found in the front panel:

**Indicative LEDs of current measure.** These leds inform of the measure shown in each display.

**Operation mode lamps.** Indicate the current operation mode of the switchboard (automatic, stop, manual, low consumption).

**Stop cycle.** This led will light up when the switchboard orders a stop cycle and will not be turned off until the stop cycle is completed. The length of the stop cycle is determined by parameters P12 and P13.

**Warm-up.** This led lights up to signal that the switchboard orders a warm-up. An acoustic alarm will notify the immediate start of the set.

**Motor ON.** Indicates that the motor is started. This is fulfilled when the voltage in any phase is superior to the threshold established by parameter P14, if a sign in the voltage entry of the battery charge alternator is superior to the value indicated by parameter P15, or when the Pick-Up Frequency of the motor is superior to the one indicated by parameter P16.

**LT closed.** This signal is active when the free voltage contact is closed and is turned off when the free voltage contact is open. In automatic mode, when the LT is closed, the switchboard will begin the start cycle. In STOP mode there will not be no change in the state of the switchboard.

**Load.** This indicator is lit up upon closing the set contactor, thus indicating that the set is working with the load. The stabilization and warm-up times of the set before activating the load are defined by parameter P11.



## **4. OPERATIONAL MODES.**

To obtain optimum performance of the set the following aspects must be emphasized:

- If the magnetic Pick-Up is installed, it should be indicated (by setting parameter P34 to "1"), that the frequency reading will be accomplished by Pick-Up. If the frequency reading is done by generator, the magnetic Pick-Up must not be connected to the switchboard.
- The switchboard has three ways of detecting a started motor: by voltage in the phases of the generator, by voltage in the battery load alternator and by the frequency of the motor Pick-Up. The switchboard detects that the motor is started if the voltage in any phase is superior to the threshold established in parameter P14, when a sign in the voltage entry of the battery load alternator is superior to the value indicated in parameter P15, or if the frequency of the motor Pick-Up is superior to the frequency indicated by parameter P16.
- The stop cycle is accomplished by observing the times established by parameters P12 and P13: the switchboard will order a stop until the stop time by excitement (P13) is accomplished, even if the set is already stopped.

The centralite can operate in four different modes, which can be selected via the AUT, STOP/RESET, MAN/START switches:

**Manual mode (MAN/START).** In this function the set can be started manually through the MAN/START switch. The protections of the motor are active at all times. The connection with the load (close set contactor) is accomplished automatically, after a delay time for the stabilization of the set; this time is definable by the user (parameter P11). From that moment on, the set contactor remains permanently locked, until a set stop is performed, or an alarm with an associated stop is detected.

**Automatic mode (AUT).** In this function the start depends on the closing of the free voltage contact LT. When this is closed, the centralite will order sequentially the start attempts indicated by parameter P09, with the length indicated by parameter P08, and with a waiting period between start attempts indicated by parameter P10.



**Stop mode (STOP/RESET).** In this mode, the generating set is stopped and remains waiting for a mode change. When maintained pressed for 5 seconds, the STOP/RESET button will accomplish a reset.

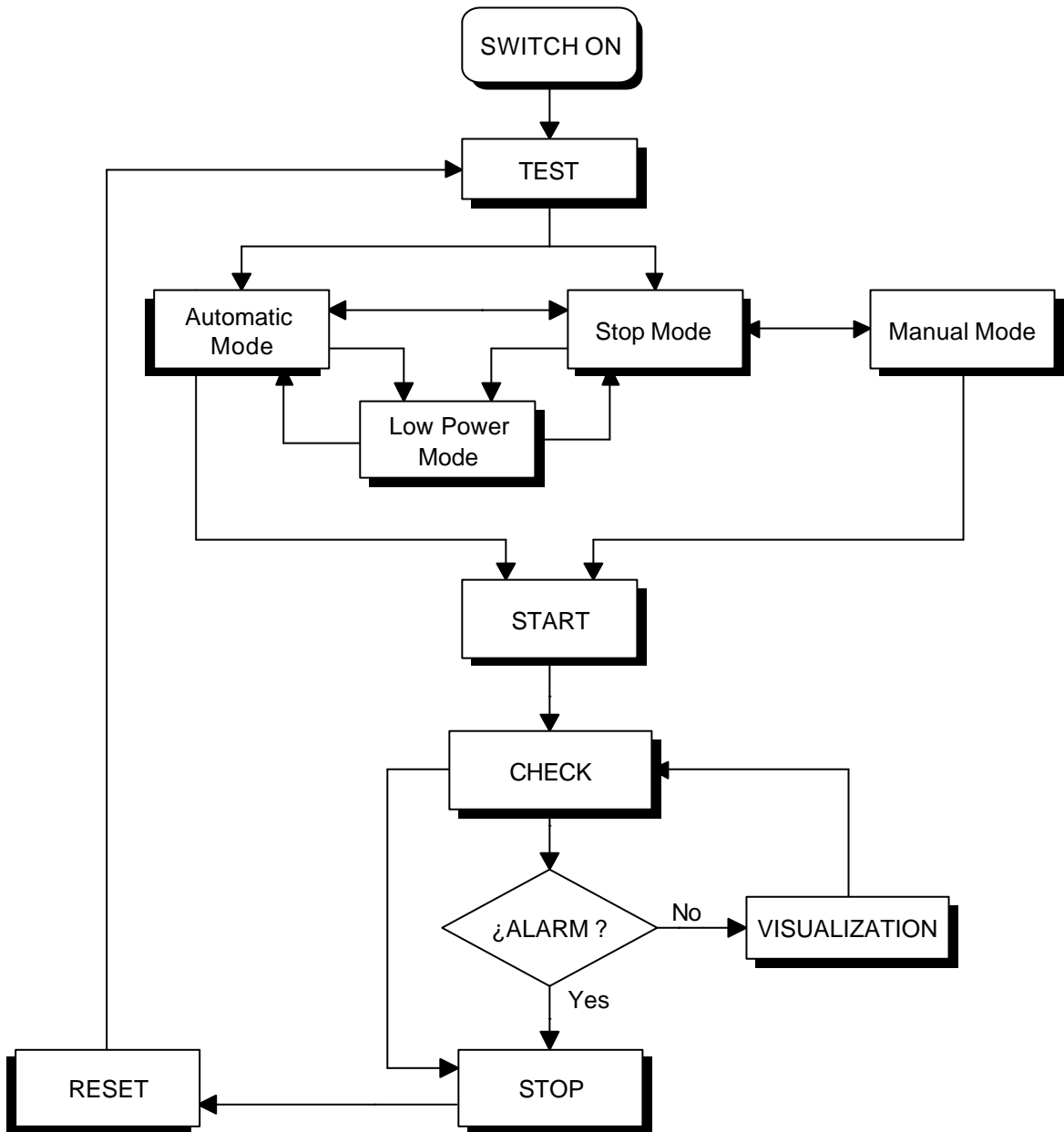
**Low power mode.** The switchboard engages this operation mode after 5 minutes on non-activity in mode stop, or when in automatic mode with the LT open for more than 5 minutes. In low power mode, the displays and the leds will turn off, except the STOP/RESET led (blinking). To exit this mode, just press any button of the switchboard.

**Note:** after disconnection or feed failure, the switchboard may begin to operate, once the feed is re-established, in either automatic or stop mode (as programmed by parameter P01).

The handling of displays showing the measures done by the switchboard is the same for the first 3 modes. To go from one measure to another, simply press the button associated with each of them, and the led lighting up in the left-hand side of the display will indicate the measure that it is being currently visualized.



The following figure shows the operation blocks of the CMD switchboard.





## **5. DESCRIPTION OF THE CONNECTING TERMINALS, GENERAL CONNECTIONS SCHEME.**

The connection terminals are placed on the back panel of the switchboard (first see figures 1a and 1b below).

**12V terminal: battery positive 12V.** The positive of the battery (if it is a 12V one) is connected to this terminal.

**24V terminal: battery positive 24V.** The positive of the battery (if it is a 24V one) is connected to this terminal.

**BAT terminal: battery negative.** The negative of the battery is connected to this terminal.

**Note:** in environments with high electromagnetic interferences, the battery must be directly wired by a 2.5 mm<sup>2</sup> twisted pair.

**LT and LT terminal: Free voltage contact.** a contact without voltage is connected to these terminals, only operative in automatic mode. If the contact passes to CLOSE position, the genset starts, if it passes to OPEN, the genset stops.

**PCK and PCK terminal: pick-up input.** The signal from the magnetic pick-up is connected to these terminals. If the set is provided with a pick-up device, parameter P34 must be set to "1", so that the frequency reading is accomplished through the pick-up. These inputs do not have polarity.

**VL1, VL2 and VL3 terminals: generator input voltage.** The phases of the alternator are connected to these terminals. The permitted maximum is 500V rms. We can have 4 different systems, programmable via parameter P04. The 4 systems are: system without phases (i.e., motor pump), monophase system, two-phase system and three-phase system. In monophase systems, we must connect between terminals VL1 and VL2; if it is 2-



phase, we will connect the two phases to VL1, VL2 and the neutral or common to VL3, if it is a 3-phase system, we will connect the three phases to VL1, VL2 and VL3.

**IL1, IL2, IL3 and N terminals: current input /5.** The secondaries of the current transformers ( /5A) must be connected to the current inputs IL1, IL2, IL3, the common conductor of the secondaries of the current transformers must be connected to terminal N, as indicated in figure 1a. These transformers will have a power superior to 1.5 VA. The transformation ratio is indicated by parameter P05.

**IMPORTANT: Before carrying out any tasks on the current transformers, verify that no current is circulating in the primary transformer, since if we open the secondary of an current transformer through which a current is circulating, extremely high voltages are produced, which can injure or even kill the person manipulating them.**

**NC terminal: fuel level.** The fuel level sensor (gauger) is connected to this input. ( variable resistance of 0 to 330 Ohm).

**P terminal: oil pressure.** The oil pressure sensor is connected to this input (VDO code 360.081/030/009).

**T terminal: water temperature.** The water temperature sensor is connected to this input (VDO code 323.803/004/001).

**DI terminal: voltage level of the battery load alternator.** Terminal D+ of the battery load alternator is connected to this input and is used to detect whether the battery load alternator is re-charging the battery. In case of failure detection, the type of action to accomplish can be programmed in the battery load alternator through parameter P24. Furthermore, this input can also detect whether the generating set is running.

**ARR terminal: start.** If a start of the motor is internally ordered, this output will activate for a maximum time programmed by P08; if the motor is found to be running during this



time, the output will become inactive. Also, the number of start attempts is programmable through parameter P09, and the time between them, through P10. An external relay, with its corresponding diodes for dissipation of inductive currents, is necessary (see figure 1b). This output sustains a maximum current of 0.5A.

**PE terminal: stop by excitation.** If a stop of the generating set is internally ordered, this output will activate for a maximum time programmed by P13. If the genset does not stop, further stops will be ordered for successive periods of equal duration until the genset stops. An external relay, with its corresponding diodes for dissipation of inductive currents, is necessary (see figure 1b). This output sustains a maximum current of 0.5A.

**PD terminal: stop by de-excitation.** The output associated with this terminal is active when the genset has to be started and is deactivated when ordered to stop. An external relay, with its corresponding diodes for dissipation of inductive currents, is necessary (see figure 1b). This contact sustains a maximum current of 0.5A.

**PR terminal: warm-up.** The output associated with this terminal is active before each start attempt during the time programmed by P07 to accomplish the warm-up of the motor. An external relay, with its corresponding diodes for dissipation of inductive currents, is necessary (see figure 1b). This contact sustains a maximum current of 0.5A.

**+BAT terminal: battery positive for outputs.** The positive of the battery is connected to this terminal. This positive supplies all the outputs from the switchboard, in addition to serving as a reference for the reading of the battery voltage.

**CON terminal: counter activation (warming of the motor).** The output associated with this terminal becomes active after the time programmed by P11, once the centralite detects that the motor has started. It is used for warming up the set without load, before putting load on it. An external relay, with its corresponding diodes for dissipation of inductive currents, is necessary (see figure 1b). This output sustains a maximum current of 0.5A.



**PUMP terminal: automatic fill-up of fuel tank.** The output associated with this terminal is active if this option is enabled through parameter P39 (auto-fill enabled) and the fuel level descends below the value indicated by parameter P40 (minimum fuel level). It is deactivated when the fuel level surpasses the value indicated in parameter P41 (maximum fuel level). An external relay, with its corresponding diodes for dissipation of inductive currents, is necessary (see figure 1b). This output sustains a maximum current of 0.5A.

**AL terminal: alarm output.** The output associated with this terminal is active when any anomaly in the set is detected, or there are values out of the range programmed in the parameters. An external relay, with its corresponding diodes for dissipation of inductive currents, is necessary (see figure 1b). This contact sustains a maximum currents of 0.5A.

**D+ terminal: Excitation of battery load alternator.** Terminal D+ of the battery load alternator of the generating set is connected to this terminal in order to excite the alternator and make it begin to load the battery.

**ATA terminal: high water temperature.** The thermostat corresponding to the water temperature of the motor is connected to this terminal. Both the delay in the checkup (P19) and the type of action (P20) are programmable. The alarm is active at low level.

**BPA terminal: low oil pressure.** The pressurestat corresponding to oil pressure of the motor is connected to this terminal. Both the delay in the checkup (P17) and the type of action (P18) are programmable. The alarm is active at low level.

**RC terminal: fuel reservoir.** The fuel reservation contact is connected to this terminal. The alarm is active at low level. The type of action after detecting low fuel reservoir is programmable (P23).

**P. EM terminal: emergency stop.** When active, an immediate stop of the generating set is performed. It can be activated (parameter P25) either through a normally open contact (NO) or through a normally closed contact (NC); in the first case, if we want to activate



the emergency stop, we will close the contact and we will put a negative on this entry. In the second case we will open the circuit and we will stop putting ground on the P. EM terminal.

**AUX terminal: Auxiliary digital INPUT.** Any sensor which can close a contact when activated can be connected to this terminal. Both the delay in the checkup (P21) and the type of action after activating this input (P22) are programmable. The alarm is active at low level.



### GENERAL CONNECTIONS SCHEME.

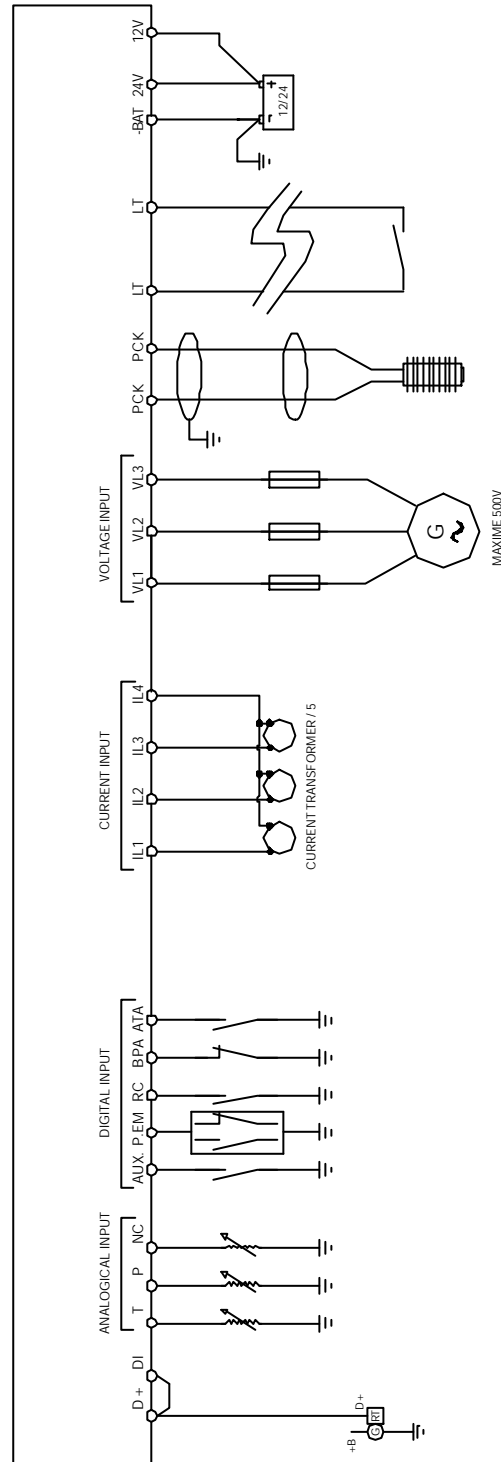


Figure 1a.

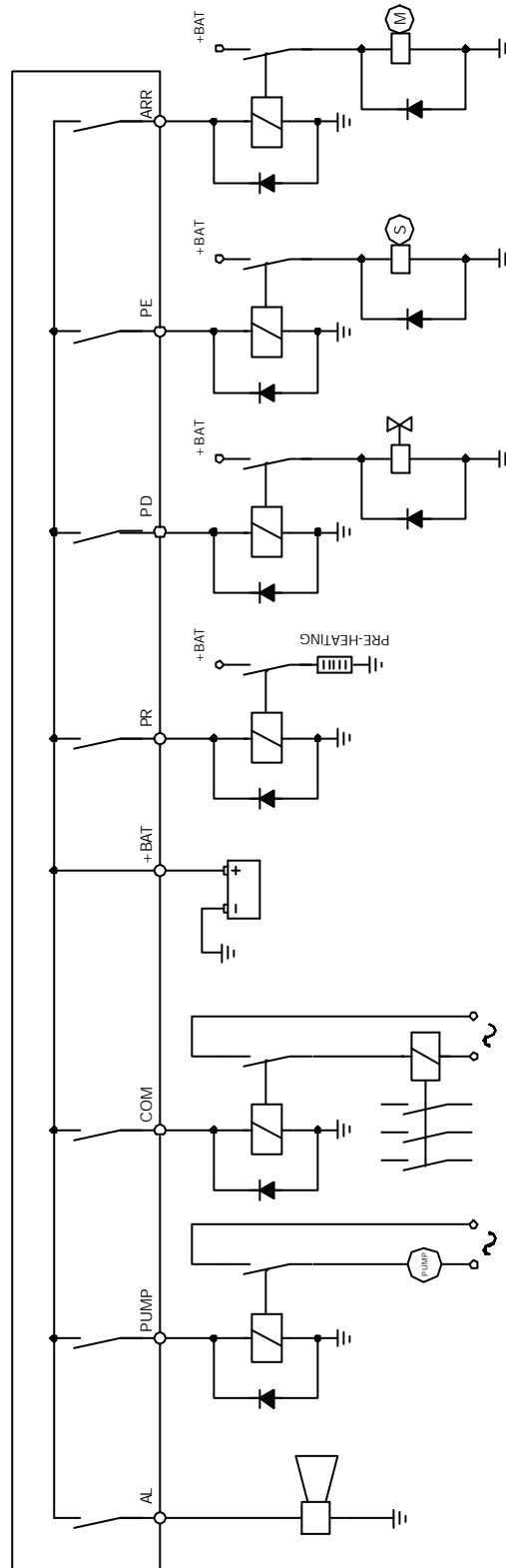


Figure 1b.



## **6. PARAMETERS, DESCRIPTION AND PROGRAMMING.**

### **LIST OF CMD PARAMETERS.**

<b>P</b>	<b>Description</b>	<b>Value</b>
P01	Mode of operation at connection (0=STOP, 1=AUT)	0
P02	No. of sprockets in motor wheel	132
P03	Nominal R.P.M. of motor	1,500 rpm
P04	Type of net (0=NO NET, 1=MONOPHASE, 2=2-PHASE, 3=3-PHASE)	3
P05	Current in the primary of the current transformers	100 A
P06	Length of acoustic alarm	20 s
P07	Warm-up time	1 s
P08	Start time	5 s
P09	No. of start attempts	3
P10	Time between start attempts	10 s
P11	Warm-up time prior to activation of load	20 s
P12	Cooling time	20 s
P13	Stop time in excitation stop	10 s
P14	Generator voltage threshold to detect motor running	100 V
P15	Battery load alternator voltage threshold to detect motor running	10 V
P16	Pick-Up frequency threshold to detect motor running	1000 Hz
P17	Delay (upon starting) of low-pressure oil checkup	10 s
P18	Action after low oil pressure alarm (A=2, A+CP=1, A+PI=0)	0 (A+PI)
P19	Delay (upon starting) of high water temperature checkup	5 s
P20	Action after high water temperature alarm (A=2, A+CP=1, A+PI=0)	0 (A+PI)
P21	Delay (upon starting) of auxiliary input checkup	10 s
P22	Action after auxiliary input alarm (A=2, A+CP=1, A+PI=0)	1 (A+CP)
P23	Action after fuel reservoir alarm (A=2, A+CP=1, A+PI=0)	2 (A)
P24	Action after battery load alternator failure (A=2, A+CP=1, A+PI=0)	2 (A)
P25	Type of contact in emergency stop (0=NO, 1=NC)	1 (NC)
P26	Maximum voltage of generator	420 V
P27	Transient time of allowance for over voltage	1.0 s
P28	Minimum voltage of generator	360 V
P29	Delay (upon starting) of minimum alternator voltage and low frequency checkup.	2.0 s
P30	Maximum asymmetry between phases	40 V
P31	Transient time of allowance for asymmetry and sub voltage	2.0 s



P32	Maximum current allowed	120 A
P33	Transient time of allowance for overcurrent	10 s
P34	Frequency reading (0=GENERATOR, 1=PICK-UP)	1
P35	Maximum frequency allowed (overspeed)	58 Hz
P36	Transient time of allowance for overfrequency	0.5 s
P37	Minimum allowed frequency (loss of speed)	45 Hz
P38	Transient time of allowance for loss of speed	2.0 s
P39	Automatic fuel tank fill (0-disabled, 1-enabled)	1
P40	Minimum fuel level	20 %
P41	Maximum fuel level	90 %
P42	Low fuel threshold (acoustic alarm)	15 %
P43	Minimum battery voltage	10 V
P44	Maximum battery voltage	16 V
P45	Transient time of allowance for battery voltage failure	3 s
P46	Action after detecting battery voltage failure (A=2, A+CP=1, A+PI=0)	2 (A)
P47	Selection of the system units (°C and bar = 0, °F and psi = 1)	0
P48	Manual fuel tank fill	
P49	Analogical measurement adjustment (set at "1" to enter adjust mode)	0

**NOTE:**

A = acoustic alarm.

A+CP = acoustic alarm and stop cycle (stop with cooling).

A+PI = acoustic alarm and immediate stop (no cooling).

**DESCRIPTION**

Each of the parameters in the of previous table is described below.

**P01. OPERATION MODE AT CONNECTION.** (0=STOP, 1=AUT). The operation mode of the centralite at the moment of connection is indicated by this parameter (see operation modes).

**P02. NUMBER OF SPROCKETS IN MOTOR WHEEL.** The number of teeth of the drive wheel of the motor is introduced by this parameter.



**P03. NOMINAL R.P.M. OF THE MOTOR.** The nominal revolutions of the motor are introduced.

**P04. TYPE OF NET. (WITHOUT NET=0, MONOPHASE=1, 2-PHASE=2, 3-PHASE=3).** By using this parameter we can choose the type of net, depending on the number of phases that we have. 4 systems can be used: system without phases (i.e., motor pump), monophasic system, two-phase system and three-phase system. In monophasic systems, we must connect between terminals VL1 and VL2; if it is 2-phase, we will connect the two phases to VL1, VL2 and the neutral or common to VL3, if it is a 3-phase system, we will connect the three phases to VL1, VL2 and VL3

**P05. CURRENT IN THE PRIMARY OF THE CURRENT TRANSFORMERS.** This parameter indicates the current that circulates in the primary of the current transformer. For example, for transformers of current 100/5 (characteristic of the current transformer), we must fix parameter P05 at value 100 ( $P05 = 100$ ).

**P06. LENGTH OF ACOUSTIC ALARM.** To make the internal alarm act non-stop, after an anomalous situation is detected, we must set this value at "0". Also, it is possible to silence the sound alarm through selector D4(-).

**P07. WARM-UP TIME.** The warm-up output of the centralite activates, before the start attempt, for the time programmed by this parameter (to warm up the fuel).

**P08. START TIME.** The starter motor will run for the maximum period of time programmed. If the motor is found to be running within this time, the output deactivates.

**P09. NUMBER OF START ATTEMPTS.** Maximum number of attempts to start the generating set.

**P10. TIME BETWEEN START ATTEMPTS.** After each start attempt and before the next one, there is a waiting time corresponding to the value assigned by this parameter.



**P11. WARM-UP TIME BEFORE ACTIVATING LOAD.** When the switchboard detects that the motor is started, there is a waiting time before activating the “CON” output: this allows the set to heat up before transferring load to it.

**P12. COOLING TIME.** Operation time of the set without load before the stop phase (the “CON” output deactivates). Not effected in the event of stop by pressing the emergency stop button through “P. EM” terminal, or if we have selected immediate stop (A+PI).

**P13. LENGTH OF THE EXCITATION STOP.** If the set is stopped by excitation, the “PE” output (from the connector in the switchboard) will be active for the time indicated by this parameter to stop the generating set.

**P14. GENERATOR VOLTAGE THRESHOLD TO DETECT MOTOR RUNNING.** When the voltage of any of the phases of the generator exceeds this value, the switchboard will acknowledge that the motor is started.

**P15. BATTERY LOAD ALTERNATOR VOLTAGE THRESHOLD TO DETECT MOTOR RUNNING.** When the voltage of the battery load alternator exceeds value, the switchboard considers that the motor is started. (This reading is accomplished through “DI” terminal). If we place this parameter to “0”, the detection of engine on is not realized by means of battery load alternator.

**P16. PICK-UP FREQUENCY THRESHOLD TO DETECT MOTOR RUNNING.** If we chose frequency reading by pick-up in parameter P34, when the frequency of the pick-up exceeds this value, the switchboard will consider that the motor is started. (This reading is accomplished through the “PCK PCK” terminals).

**P17. DELAY (UPON STARTING) OF LOW OIL PRESSURE (BPA) CHECK-UP.** Once the motor is detected operating, there is a delay of this time before beginning to check any possible decrease in oil pressure: this allows for the progressive increase of oil pressure.

**P18. ACTION AFTER LOW OIL PRESSURE (BPA) ALARM. (A=2, A+CP=1, A+PI=0).**

When a failure in oil pressure is detected, the type of action to accomplish may be: just acoustic alarm (A), acoustic alarm + stop with cooling time (A+CP), acoustic alarm + immediate stop (A+PI).

**P19. DELAY (UPON STARTING) OF HIGH WATER TEMPERATURE (ATA) CHECK-**

**UP.** Once the motor is under way, there is a delay time before beginning to check high water temperature.

**P20. ACTION AFTER HIGH WATER TEMPERATURE (ATA) ALARM. (A=2, A+CP=1,**

**A+PI=0).** After high water temperature failure, the type of action to accomplish may be: only acoustic alarm (A), acoustic alarm + stop with cooling (A+CP), acoustic alarm + immediate stop (A+PI).

**P21. DELAY (UPON STARTING) OF AUXILIARY INPUT (AUX) CHECK-UP.**

Once the motor is detected under way, there is a delay time before beginning to check the auxiliary input.

**P22. ACTION AFTER AUXILIARY INPUT (AUX) ALARM. (A=2, A+CP=1, A+PI=0).**

When a failure occurs in the auxiliary input (AUX), the of action to accomplish can be: a simple acoustic alarm (A), acoustic alarm + stop with cooling (A+CP) or acoustic alarm + immediate stop (A+PI).

**P23. ACTION AFTER FUEL RESERVOIR ALARM. (A=2, A+CP=1, A+PI=0).**

a simple acoustic alarm (A), acoustic alarm + stop with cooling (A+CP) or acoustic alarm + immediate stop (A+PI).

**P24. ACTION AFTER FAILURE OF THE BATTERY LOAD ALTERNATOR. (A=2,**

**A+CP=1, A+PI=0).** If a failure (or a possible strap breakage) is detected in the battery load alternator, we can choose the type of action to accomplish: only acoustic alarm (A), acoustic alarm + stop with cooling (A+CP), acoustic alarm + immediate stop (A+PI). The failure of the battery load alternator is detected by the "DI" terminal.



**P25. TYPE OF CONTACT IN EMERGENCY STOP. ( NO=0, NC=1).** The type of contact in emergency stop may be selected: either a usually open contact NO or a usually closed contact NC: in the first case, when we want to activate the emergency stop we will close the contact and we will put a negative on this input. In the second case, we will open the circuit and we will stop transferring ground to the P. EM terminal.

**P26. MAXIMUM VOLTAGE OF GENERATOR.** Here, we will introduce the maximum generator voltage that we want to permit.

**P27. TRANSIENT TIME OF ALLOWANCE FOR OVERVOLTAGE.** If the voltage exceeds the maximum value for a time superior to specified by this parameter, an immediate stop of the set is ordered (A+PI).

**P28. MINIMUM VOLTAGE OF GENERATOR.** We will introduce the minimal value that we are ready to permit.

**P29. DELAY (UPON STARTING) OF MINIMUM ALTERNATOR VOLTAGE AND LOW FREQUENCY CHECK-UP.** After the motor is detected under way, there is a delay before check-ups for minimum voltage failure and low frequency starts, to allow time for the set to increase revolutions.

**P30. MAXIMUM ASYMMETRY BETWEEN PHASES.** The asymmetry is the difference in voltage between any two phases of the generator. The asymmetry is only taken into account in 3-phase mode.

**P31. TRANSIENT TIME OF ALLOWANCE FOR ASSYMETRY AND SUBVOLTAGE.** When asymmetry is exceeded, or the generator voltage is inferior to the minimum value, for a time longer than specified, an immediate stop of the set is ordered (A+PI).

**P32. MAXIMUM CURRENT ALLOWED.** The maximum current that we want to allow in circulation in any of the phases of the generator is introduced by this parameter.



**P33. TRANSIENT TIME OF ALLOWANCE FOR OVERCURRENT.** If the current is superior to the maximum value, for a time longer than specified, a stop with cooling of the set is ordered (A+CP).

**P34. FREQUENCY READING: (0=GENERADOR, 1=PICK-UP).** If the set includes a magnetic Pick-Up device and it is connected to the switchboard, the frequency reading should be done by the Pick-Up (this parameter must be fixed at "1"). If we do not have Pick-Up or it is not connected to the switchboard, then the frequency reading must be accomplished by the generator (that is to say, this parameter must be "0").

**P35. MAXIMUM FREQUENCY ALLOWED (OVERSPEED).** When the frequency of the generator exceeds the value programmed in this parameter for a time superior to that programmed in the following parameter, a stop by excess of revolutions (r.p.m.) of the generating set occurs.

**P36. TRANSIENT TIME OF ALLOWANCE FOR OVER FREQUENCY.** When the maximum frequency is exceeded for a time superior to that specified in this parameter, an immediate stop of the set (A+PI) is ordered.

**P37. MINIMUM ALLOWED FREQUENCY (LOSS OF SPEED).** When the frequency of the generator descends below the value programmed in this parameter and for a period of time longer than that programmed by the following parameter, a stop by loss of speed of the generating set is produced.

**P38. TRANSIENT TIME OF ALLOWANCE FOR LOSS OF SPEED.** If the frequency of the set descends below minimum for a time superior to the specification of this parameter, an immediate stop of the set (A+PI) is ordered.

**P39. AUTOMATIC FUEL TANK FILL. (0=DISABLED, 1=ENABLED).** It is possible to enable or disable the automatic fuel tank fill: "0" will disable it and "1" will enable it.



**P40. MINIMUM FUEL LEVEL.** If parameter P39 is enabled, when the fuel level is below the value indicated in this parameter the PUMP output will be activated and if the system is installed the fuel tank will start to fill.

**P41. MAXIMUM FUEL LEVEL.** If parameter P39 is enabled, when the fuel level is above of the value indicated by this parameter the PUMP output will be deactivated.

**P42. LOW FUEL LEVEL THRESHOLD.** When the fuel level is below the value indicated in this parameter the acoustic alarm will be activated and alarm E07 (low fuel level) will be shown.

**P43. MINIMUM BATTERY VOLTAGE.** The minimum voltage level wished for the battery is introduced by this parameter.

**P44. MAXIMUM BATTERY VOLTAGE.** The MAXIMUM voltage level wished for the battery is introduced by this parameter.

**P45. TRANSIENT TIME OF ALLOWANCE FOR BATTERY VOLTAGE FAILURE.** If the battery voltage is out of the margins established by the two previous parameters (P43, P44) for a time superior to specified, the battery voltage failure circuit will activate and the action that we indicate in the following parameter will be accomplished (P46).

**P46. ACTION AFTER DETECTING BATTERY VOLTAGE FAILURE. (A=2, A+CP=1, A+PI=0).** The battery failure having being detected for a time superior to what is indicated in P45, the type of action to accomplish can be chosen: either an acoustic alarm (A), or an acoustic alarm + stop with cooling (A+CP), or an acoustic alarm + immediate stop (A+PI).

**P47. SELECTION OF THE SYSTEM OF UNITS.** If in this parameter we place "0" the measurements of pressure and temperature will indicate them to us in °C and bar, if we place one "1" the measurements of pressure and temperature will indicate them to us in F and psi.



**P48. MANUAL FUEL TANK FILL.** If we want to activate manually the fuel pump output (PUMP output), we will proceed as follows: after enter the parameters adjustment mode, we will direct ourselves to parameter P48 and we will keep the A (+) button pressed. While the button is pressed, the PUMP output will be active.

**P49. ANALOGICAL MEASUREMENT ADJUSTMENT.** (set at "1" to enter adjust mode). To adjust the analogical measurements, proceed in the following way: enter parameters adjustment, go to P49 and set it at "1". Then, press the stop/reset button and automatically enter measurement adjustment mode. Start the genset and choose the measurement to adjust with the V( $\uparrow$ ) button. Once this accomplished, buttons A(+) and D4(-) will let us varying its value until reaching the desired level. To adjust other values, press the V( $\uparrow$ ) button again until the led corresponding to that measure is lit and use the buttons A(+) and D4(-) to adjust it. Once all the desired measurements have been adjusted, press again the stop/reset selector: the switchboard stops the set and memorizes the new adjustments.

### **PROGRAMMING MODE.**

To program parameters, proceed as follows: press the stop/reset selector for over 5 seconds and the switchboard will do a reset. While displays and leds are being tested, press buttons V( $\uparrow$ ) and D3( $\downarrow$ ) simultaneously to enter the parameters programming mode. The parameter number will show in the top left display (display 1). For example, P01, and the corresponding value will appear in the top right display (display 2). To change parameter use buttons V( $\uparrow$ ) and D3( $\downarrow$ ) and to change the value of the parameter, A(+) and D4(-). A(+) will increase the value of the parameter and D4(-) will reduce it. When we finish the modification of the parameters we will pulsate the stop/reset selector and all the modifications will be kept in non-volatile memory, that is to say, will remain though the switchboard is shut off.



## **7. CALIBRATING AND ANALOGICAL READINGS ADJUSTMENT.**

For calibration, proceed as follows: enter programming mode (follow the steps listed in the previous paragraph) and go to parameter P49. ANALOGICAL MEASUREMENTS ADJUSTMENT. (set at "1" to enter adjustments mode). To adjust the analogical measurements, proceed in the following way: enter parameters adjustment, go to P49 and fix it at "1"; then press the stop/reset button and automatically enter measurements adjustment mode. All the leds will remain turned off except L1-L2 of display 1, which is the first measurement to be adjusted.

Then start the genset in the usual way, by pressing the START/MAN button or, if we are in automatic mode, by closing the free voltage contact LT. The switchboard will accomplish the start process and when the set is detected running, all visualizations will be turned off, except display 1, which will show the value of the voltage measurement L1-L2, the first to adjust. The switchboard will carry out , until end the adjustment, all the protections except those related to the analogical measurements to be adjusted (over- and sub-voltage, asymmetry and overcurrent).

Use button  $V(\uparrow)$  to select the measurement that we want to adjust and vary its value by using selectors A(+) and D4(-). To adjust other values, press  $V(\uparrow)$  again until the corresponding led lights up and adjust it with the selectors A(+) and D4(-). Once we have adjusted all the desired measurements, press the stop/reset selector and the switchboard will memorize the new adjustments in non-volatile memory and order a stop cycle of the genset. Visualizations and leds will go back to normal operation.

If, during parameters adjustment, an alarm with associated stop is produced, the switchboard abandons the adjustment mode immediately and performs the corresponding type of stop, with all visualizations returning to normal operating conditions.



## **8. ALARMS AND ALARMS CODE.**

### **ALARMS**

<b>E</b>	<b>Description</b>
E00	Correct operation
E01	High water temperature
E02	Low oil pressure
E03	Auxiliary input failure
E04	Battery load alternator failure
E05	Start failure
E06	Motor failure
E07	Low fuel level
E08	Fuel reservoir
E09	Overvoltaje
E10	Subvoltaje
E11	Asymmetry between phases
E12	Overcurrent
E13	Overfrequency
E14	Subfrequency
E15	High battery voltage
E16	Low battery voltage
E17	Emergency stop

**E01.- High water temperature (ATA).** Indicates that the thermostat of the motor has detected an anomaly.

**E02.- Low oil pressure (BPA).** Indicates that the pressurestat of the motor has detected an anomaly.

**E03.- Failure in auxiliary input (AUX).** Indicates that the auxiliary input of the motor has detected an anomaly.

**E04.- Battery load alternator failure (D +).** Indicates that the battery load alternator is not re-charging the battery, once the motor started.



**E05.- Start failure.** Indicates that the switchboard has effected all the programmed start attempts of the motor, after which no effective start has occurred.

**E06.- Motor failure.** Indicates that the motor has stopped without the switchboard having ordered so.

**E07.- Low fuel level.** Indicates that the fuel level is inferior to that indicated by parameter P42 (low fuel level threshold). The analogical signal originates in the fuel level sensor (gauger).

**E08.- Fuel reservoir.** Indicates that the fuel tank is nearly empty. The signal originates in a digital level contact.

**E09.- Over voltage.** Indicates that the generator has produced a voltage superior to that indicated by parameter P26, and for a time superior to that of parameter P27.

**E10.- Low voltage.** Indicates that the generator has had an inferior voltage to the one indicated in parameter P28 and for a time superior to that of parameter P31.

**E11.- Asymmetry.** Indicates that there has been a difference of voltage superior to the indicated in the parameter P30 between the phases of the generator, and for a time superior to that of parameter P31.

**E12.- Overcurrent.** Indicates that an current superior to that indicated in parameter P32 has circulated in the phases of the generator, for a time superior to that of parameter P33.

**E13.- Overfrequency (overspeed).** Indicates that the frequency provided by the generator or by the pick-up (depending on the configuration of P34) exceeds the limit value indicated in parameter P35, for a time superior to that of parameter P36.



**E14.- Subfrequency (Loss of speed).** Indicates that the frequency provided by the generator or by the pick-up (depending on the configuration of P34) is inferior to the value indicated in parameter P37, for a time superior to that of parameter P38.

**E15.- High battery voltage.** Indicates that the battery exceeds the limit value indicated in parameter P44 for a time superior to that of parameter P45.

**E16.- Low battery voltage.** Indicates that the battery has a value of inferior voltage to indicate in the parameter P43 and during a time superior to the parameter P45.

**E17.- Emergency stop.** Indicates that the switchboard has accomplished an emergency stop ordered through terminal P. EM.

**9. - TECHNICAL DATA.**

<b>Description</b>	<i>Min.</i>	<i>Typ.</i>	<i>Max.</i>	<i>Un</i>
Voltage supply 12 v.	8,5	12	15	V
Voltage supply 24 v.	20	24	28	V
Maximum consumption (stand by)		220		mA
Maximum consumption (low power mode)		40		mA
Current of any output (transistor)			500	mA
Capacity of D+ output (transistor)			500	mA
Input for set voltage measurement	0		500	Vac
input for current measurement	0		5	Aac
fuel level resistance	0		330	Ohm
Operating temperature	0	+25	+60	°C
panel assembly hole		175 x 125		mm
depth for assembly		65		mm

All outputs must be endowed with appropriate devices for the elimination of inductive currents (diodes, varistors, RC filters, etc.).

All moving wiring must be kept at a safety distance from elevated electrical fields: at least 50cm from lines up to 600 A, and 100cm from lines of over 600 A.